

The MPE (Minimal Polynomial  
Extrapolation) and Vector- $\epsilon$  Methods:  
Numerical Demonstration of their Equivalence  
in Certain Cases

Yoshio Takane  
McGill University

## 1 Introduction

We exemplify the equivalence between the MPE acceleration method and the vector  $\epsilon$  ( $v$ - $\epsilon$ ) method when the iterate is linear and the exact  $k$  is chosen. General results have been given in McLeod (1971), and Graves-Morris (1983) among others, as discussed by Smith et al. (1987). Let

$$\mathbf{x}^{(q+1)} = \mathbf{H}\mathbf{x}^{(q)} + \mathbf{b} \quad (1)$$

represent the basic iterate, where it is assumed that the largest absolute eigenvalue of  $\mathbf{H}$  is strictly smaller than unity. The closed-form solution to the above system is given by

$$\mathbf{s} = \mathbf{x}^{(\infty)} = (\mathbf{I} - \mathbf{H})^{-1}\mathbf{b}, \quad (2)$$

where  $\mathbf{I} - \mathbf{H}$  is nonsingular.

Let

$$\mathbf{u}^{(q)} = \mathbf{x}^{(q+1)} - \mathbf{x}^{(q)}. \quad (3)$$

In the MPE method,  $k$  represents the order of minimal polynomials that annihilates  $\mathbf{u}^{(0)}$ . Let

$$\mathbf{U} = [\mathbf{u}^{(0)}, \dots, \mathbf{u}^{(k-1)}]. \quad (4)$$

We define  $\mathbf{c} = (c_0, \dots, c_{k-1}, 1)'$  by

$$\mathbf{c} = \begin{pmatrix} -\mathbf{U}^+ \mathbf{u}^{(k)} \\ 1 \end{pmatrix}. \quad (5)$$

In the MPE method,  $\mathbf{s}$  is obtained by

$$\mathbf{s} = \mathbf{X}\mathbf{c}/d, \quad (6)$$

where  $\mathbf{X} = [\mathbf{x}^{(0)}, \dots, \mathbf{x}^{(k)}]$ , and  $d = \mathbf{1}'_{k+1}\mathbf{c}$ .

In the  $v$ - $\epsilon$  method, we define  $\epsilon_{-1}^{(q)} = \mathbf{0}$ ,  $\epsilon_0^{(q)} = \mathbf{x}^{(q)}$  for  $q = 0, 1, \dots$ , and

$$\epsilon_{k+1}^{(q)} = \epsilon_{k-1}^{(q+1)} + (\epsilon_k^{(q+1)} - \epsilon_k^{(q)})^{-1}, \quad (7)$$

where the inverse of a vector  $\mathbf{a}$  is defined to be

$$\mathbf{a}^{-1} = \mathbf{a}/\mathbf{a}'\mathbf{a}. \quad (8)$$

(This is called the Samelson inverse of  $\mathbf{a}$ , and is equal to the transpose of the Moore-Penrose inverse of  $\mathbf{a}$  considered as a matrix.) Then,

$$\mathbf{s} = \epsilon_{2k}^{(0)}. \quad (9)$$

## 2 Demonstrations of the equivalences

### 2.1 A case of scalar variable

We assume there is a single variable in  $\mathbf{x}$ , which will be denoted as  $x$ . Suppose we have the following updating formula:

$$x^{(q+1)} = (1/2)x^{(q)} + 1. \quad (10)$$

the closed form solution to this system is  $s = 1/(1/2) = 2$ . Suppose that the iteration starts at  $x^{(0)} = 0$ . Then we have

Table 1: Successive updates of  $x^{(q)}$  and resultant  $u^{(q)}$ .

$x^{(0)}$	$x^{(1)}$	$x^{(2)}$
0	1	1.5
$u^{(0)}$	$u^{(1)}$	
1	.5	

In the MPE method, we obtain  $\mathbf{c}_0 = -u^{(1)}/u^{(0)} = -.5$ , and  $c_1 = 1$  (by definition). so that

$$s = \frac{c_0x^{(0)} + c_1x^{(1)}}{c_0 + c_1} = \frac{-.5(0) + 1(1)}{-.5 + 1} = 2. \quad (11)$$

The general formula for  $s$  is given by

$$s = \frac{x^{(0)}u^{(1)} - x^{(1)}u^{(0)}}{u^{(1)} - u^{(0)}}. \quad (12)$$

In the v- $\epsilon$  method, we would like to get

$$\epsilon_2^{(0)} = \epsilon_0^{(1)} + (\epsilon_1^{(1)} - \epsilon_1^{(0)})^{-1},$$

where

$$\begin{aligned}\epsilon_0^{(1)} &= x^{(1)}, \\ \epsilon_1^{(1)} &= \epsilon_{-1}^{(2)} + (\epsilon_0^{(2)} - \epsilon_0^{(1)})^{-1},\end{aligned}$$

and

$$\epsilon_1^{(0)} = \epsilon_{-1}^{(1)} + (\epsilon_0^{(1)} - \epsilon_0^{(0)})^{-1}.$$

See Table 2 below. We have

$$\epsilon_1^{(0)} = (u^{(0)})^{-1} = (1)^{-1} = 1,$$

and

$$\epsilon_1^{(1)} = (u^{(1)})^{-1} = (.5)^{-1} = 2,$$

so that

$$\epsilon_2^{(0)} = s = x^{(1)} + ((u^{(1)})^{-1} - (u^{(0)})^{-1})^{-1} = 1 + (2 - 1)^{-1} = 1 + 1 = 2.$$

Table 2: The  $\epsilon$  table for the  $v$ - $\epsilon$  method.

$k = -1$	$k = 0$	$k = 1$	$k = 2$
$\epsilon_{-1}^{(0)} = 0$	$\epsilon_0^{(0)} = x^{(0)}$		
$\epsilon_{-1}^{(1)} = 0$	$\epsilon_0^{(1)} = x^{(1)}$	$\epsilon_1^{(0)} = (u^{(0)})^{-1}$	
$\epsilon_{-1}^{(2)} = 0$	$\epsilon_0^{(2)} = x^{(2)}$	$\epsilon_1^{(1)} = (u^{(1)})^{-1}$	$\epsilon_2^{(0)}$

The general formula for  $s$  is given by

$$\begin{aligned}
s &= x^{(1)} + ((u^{(1)})^{-1} - (u^{(0)})^{-1})^{-1} \\
&= x^{(1)} + \frac{u^{(0)}u^{(1)}}{u^{(0)} - u^{(1)}} \\
&= \frac{u^{(0)}x^{(1)} - u^{(1)}x^{(1)} + u^{(0)}u^{(1)}}{u^{(0)} - u^{(1)}} \\
&= \frac{x^{(0)}u^{(1)} - x^{(1)}u^{(0)}}{u^{(1)} - u^{(0)}}, \tag{13}
\end{aligned}$$

which is identical to (12).

The above line of argument remains essentially the same if we start from a different value of  $x^{(0)}$ , for example,  $x^{(0)} = -1$ .

## 2.2 A two-variable case

We consider

$$\mathbf{x}^{(q+1)} = \begin{bmatrix} .7 & 0 \\ 0 & .3 \end{bmatrix} \mathbf{x}^{(q)} + \begin{pmatrix} 1 \\ 2 \end{pmatrix}. \tag{14}$$

(Matrix  $\mathbf{H}$  may be assumed diagonal without loss of generality.) The closed-form solution is given by

$$\mathbf{s} = \begin{pmatrix} 3.3333 \\ 2.8571 \end{pmatrix}. \tag{15}$$

We obtain the following table.

For the MPE method with  $k = 2$ , we have

$$\mathbf{c} = \begin{pmatrix} -[\mathbf{u}^{(1)}, \mathbf{u}^{(2)}]^{-1} \mathbf{u}^{(3)} \\ 1 \end{pmatrix} = \begin{pmatrix} .21 \\ -1 \\ 1 \end{pmatrix}. \tag{16}$$

Table 3: Successive updates of  $\mathbf{x}^{(q)}$  and resultant  $\mathbf{u}^{(q)}$  for the two-variable case.

$\mathbf{x}^{(0)}$	$\mathbf{x}^{(1)}$	$\mathbf{x}^{(2)}$	$\mathbf{x}^{(3)}$	$\mathbf{x}^{(4)}$
0	1	1.7	2.19	2.533
0	2	2.6	2.78	2.834
$\mathbf{u}^{(0)}$	$\mathbf{u}^{(1)}$	$\mathbf{u}^{(2)}$	$\mathbf{u}^{(3)}$	
1	.7	.49	.343	
2	.6	.18	.054	

Thus,

$$\mathbf{s} = \left\{ .21 \begin{pmatrix} 0 \\ 0 \end{pmatrix} - 1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 1 \begin{pmatrix} 1.7 \\ 2.6 \end{pmatrix} \right\} / .21 = \begin{pmatrix} .7 \\ .6 \end{pmatrix} / .21 = \begin{pmatrix} 3.3333 \\ 2.8571 \end{pmatrix}. \quad (17)$$

For the  $v$ - $\epsilon$  method, we would like to get

$$\epsilon_4^{(0)} = \epsilon_2^{(1)} + (\epsilon_3^{(1)} - \epsilon_3^{(0)})^{-1},$$

where

$$\epsilon_2^{(1)} = \epsilon_0^{(2)} + (\epsilon_1^{(2)} - \epsilon_1^{(1)})^{-1},$$

$$\epsilon_3^{(1)} = \epsilon_1^{(2)} + (\epsilon_2^{(2)} - \epsilon_2^{(1)})^{-1},$$

and

$$\epsilon_3^{(0)} = \epsilon_1^{(1)} - (\epsilon_2^{(1)} - \epsilon_2^{(0)})^{-1}.$$

The  $\epsilon_2^{(q)}$  for  $q = 0, 1, 2$  we need to calculate  $\epsilon_3^{(q)}$  for  $q = 0, 1$ , on the other hand, are obtained by

$$\epsilon_2^{(0)} = \epsilon_0^{(1)} + (\epsilon_1^{(1)} - \epsilon_1^{(0)})^{-1},$$

$$\epsilon_2^{(1)} = \epsilon_0^{(2)} + (\epsilon_1^{(2)} - \epsilon_1^{(1)})^{-1},$$

and

$$\epsilon_2^{(2)} = \epsilon_0^{(3)} + (\epsilon_1^{(3)} - \epsilon_1^{(2)})^{-1}.$$

The  $\epsilon_1^{(q)}$  for  $q = 0, 1, 2, 3$ , in turn, are obtained by  $\epsilon_{-1}^{(q+1)} + (\epsilon_0^{(q+1)} - \epsilon_0^{(q)})^{-1}$ .

See Table 4 below.

Table 4: The  $\epsilon$  table for the v- $\epsilon$  method.

$k = -1$	$k = 0$	$k = 1$	$k = 2$	$k = 3$	$k = 4$
$\epsilon_{-1}^{(0)} = \mathbf{0}$					
	$\epsilon_0^{(0)} = \mathbf{x}^{(0)}$				
$\epsilon_{-1}^{(1)} = \mathbf{0}$		$\epsilon_1^{(0)} = (\mathbf{u}^{(0)})^{-1}$			
	$\epsilon_0^{(1)} = \mathbf{x}^{(1)}$		$\epsilon_2^{(0)}$		
$\epsilon_{-1}^{(2)} = \mathbf{0}$		$\epsilon_1^{(1)} = (\mathbf{u}^{(1)})^{-1}$		$\epsilon_3^{(0)}$	
	$\epsilon_0^{(2)} = \mathbf{x}^{(2)}$		$\epsilon_2^{(1)}$		$\epsilon_4^{(0)}$
$\epsilon_{-1}^{(3)} = \mathbf{0}$		$\epsilon_1^{(2)} = (\mathbf{u}^{(2)})^{-1}$		$\epsilon_3^{(1)}$	
	$\epsilon_0^{(3)} = \mathbf{x}^{(3)}$		$\epsilon_2^{(2)}$		
$\epsilon_{-1}^{(4)} = \mathbf{0}$		$\epsilon_1^{(3)} = (\mathbf{u}^{(3)})^{-1}$			
	$\epsilon_0^{(4)} = \mathbf{x}^{(4)}$				

We have

$$\epsilon_1^{(q)} = (\mathbf{u}^{(q)})^{-1}$$

for  $q = 0, 1, 2, 3$ , where

$$(\mathbf{u}^{(0)})^{-1} = \begin{pmatrix} .2 \\ .4 \end{pmatrix}, \quad (\mathbf{u}^{(1)})^{-1} = \begin{pmatrix} .8235 \\ .7059 \end{pmatrix},$$

$$(\mathbf{u}^{(2)})^{-1} = \begin{pmatrix} 1.7982 \\ .6606 \end{pmatrix}, \quad (\mathbf{u}^{(3)})^{-1} = \begin{pmatrix} 2.8449 \\ .4479 \end{pmatrix},$$

$$\begin{aligned} \epsilon_2^{(0)} &= \mathbf{x}^{(1)} + ((\mathbf{u}^{(1)})^{-1} - (\mathbf{u}^{(0)})^{-1})^{-1} \\ &= \begin{pmatrix} 1 \\ 2 \end{pmatrix} + \left( \begin{pmatrix} .8235 \\ .7059 \end{pmatrix} - \begin{pmatrix} .2 \\ .4 \end{pmatrix} \right)^{-1} = \begin{pmatrix} 2.2927 \\ 2.6341 \end{pmatrix}, \end{aligned}$$

$$\begin{aligned} \epsilon_2^{(1)} &= \mathbf{x}^{(2)} + ((\mathbf{u}^{(2)})^{-1} - (\mathbf{u}^{(1)})^{-1})^{-1} \\ &= \begin{pmatrix} 1.7 \\ 2.6 \end{pmatrix} + \left( \begin{pmatrix} 1.7982 \\ .6606 \end{pmatrix} - \begin{pmatrix} .8235 \\ .7059 \end{pmatrix} \right)^{-1} = \begin{pmatrix} 2.7238 \\ 2.5524 \end{pmatrix}, \end{aligned}$$

and

$$\begin{aligned} \epsilon_2^{(2)} &= \mathbf{x}^{(3)} + ((\mathbf{u}^{(3)})^{-1} - (\mathbf{u}^{(2)})^{-1})^{-1} \\ &= \begin{pmatrix} 2.19 \\ 2.78 \end{pmatrix} + \left( \begin{pmatrix} 2.8449 \\ .4479 \end{pmatrix} - \begin{pmatrix} 1.7982 \\ .606 \end{pmatrix} \right)^{-1} = \begin{pmatrix} 3.1075 \\ 2.5936 \end{pmatrix}. \end{aligned}$$

Finally,

$$\begin{aligned} \epsilon_3^{(0)} &= (\mathbf{u}^{(1)})^{-1} + (\mathbf{u}^{(1)} + ((\mathbf{u}^{(2)})^{-1} - (\mathbf{u}^{(1)})^{-1})^{-1} - ((\mathbf{u}^{(1)})^{-1} - (\mathbf{u}^{(0)})^{-1})^{-1})^{-1} \\ &= \begin{pmatrix} 3.0625 \\ .2813 \end{pmatrix}, \end{aligned}$$

$$\begin{aligned} \epsilon_3^{(1)} &= (\mathbf{u}^{(2)})^{-1} + (\mathbf{u}^{(2)} + ((\mathbf{u}^{(3)})^{-1} - (\mathbf{u}^{(2)})^{-1})^{-1} - ((\mathbf{u}^{(2)})^{-1} - (\mathbf{u}^{(1)})^{-1})^{-1})^{-1} \\ &= \begin{pmatrix} 4.3750 \\ .9375 \end{pmatrix}, \end{aligned}$$

and

$$\epsilon_4^{(0)} = \begin{pmatrix} 2.7238 \\ 2.5524 \end{pmatrix} + \left( \begin{pmatrix} 4.3750 \\ .9375 \end{pmatrix} - \begin{pmatrix} 3.0625 \\ .2813 \end{pmatrix} \right)^{-1} = \begin{pmatrix} 3.3333 \\ 2.8571 \end{pmatrix}.$$



Again, we get an identical result from the two methods.

A general formula for  $\epsilon_4^{(0)}$  is given by

$$\begin{aligned} \epsilon_4^{(0)} = & \mathbf{x}^{(2)} + ((\mathbf{u}^{(2)})^{-1} - (\mathbf{u}^{(1)})^{-1})^{-1} + \\ & \{(\mathbf{u}^{(2)})^{-1} + (\mathbf{u}^{(2)} + ((\mathbf{u}^{(3)})^{-1} - (\mathbf{u}^{(2)})^{-1})^{-1} - ((\mathbf{u}^{(2)})^{-1} - (\mathbf{u}^{(1)})^{-1})^{-1})^{-1} \\ & - (\mathbf{u}^{(1)})^{-1} - (\mathbf{u}^{(1)} + ((\mathbf{u}^{(2)})^{-1} - (\mathbf{u}^{(1)})^{-1})^{-1} - ((\mathbf{u}^{(1)})^{-1} - (\mathbf{u}^{(0)})^{-1})^{-1})^{-1}\}^{-1}. \end{aligned} \tag{18}$$

This should theoretically be identical to (Smith, et al., 1987, Sect. 5)

$$\mathbf{s} = \sum_{q=0}^k \gamma_q \mathbf{x}^{(q)},$$

where

$$\gamma_q = c_q / \sum_{j=1}^k c_j,$$

although it is by no means obvious from these formulas.

## References

- Graves-Morris, P. R. (1983). Vector valued rational interpolants I. *Numerische Mathematik*, **42**, 331-348.
- McLeod, J. B. (1971). A note on the  $\epsilon$ -algorithm. *Computing*, **7**, 17-24.
- Smith, D. A., Ford, W. F., and Sidi, A. (1987). Extrapolation methods for vector sequences. *SIAM Review*, **29**, 199-233.